

9. Let  $A_{ij}$  be the cofactor of the element  $a_{ij}$  in the matrix  $A = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$  with  $\det(A) = 5$ .

The value of the expression  $a_{11}A_{11} + a_{12}A_{12} + a_{21}A_{21} + a_{22}A_{22}$  then is equal to

A. 0

B. 5

C. 10

D. 15

E. undetermined by the information given above

$$\det A = a_{11}A_{11} + a_{12}A_{12} = \text{expansion along row 1}$$

$$\det A = a_{21}A_{21} + a_{22}A_{22} = \text{expansion along row 2}$$

$$\text{So this is } 2 \times \det A = 10$$

10. Let  $A = \begin{bmatrix} 1 & k \\ k & 3 \end{bmatrix}$  and  $b = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ . The values of  $k$  for which the system  $Ax = b$  has a unique solution are

A.  $k \neq \sqrt{6}$

B.  $k \neq \{\sqrt{3}, -\sqrt{3}\}$

C.  $k = \{\sqrt{2}, -\sqrt{2}\}$

D. All real numbers

E. None of the above

The system has a unique solution

only if the matrix has an inverse

$$\det \begin{bmatrix} 1 & k \\ k & 3 \end{bmatrix} \neq 0 \quad 3 - k^2 \neq 0$$

$$k \neq \sqrt{3}, \quad k \neq -\sqrt{3}$$

Newton's Law of Cooling:  $M$  = temperature of The ambient,  $T(t)$  = temperature of the object

$$\frac{dT}{dt} = k(M - T), \quad k > 0; \quad \frac{1}{M - T} dT = k dt$$

$$- \ln |M - T(t)| = kt + C \quad |M - T(t)| = e^{-kt} \cdot e^C \quad \cancel{M - T(t)} = (M - T(0)) e^{-kt}$$

$$M - T(t) = (M - T(0)) e^{-kt} \quad \cancel{M - T(t)} = \text{B}$$

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2. A ranger in a national park found at noon the body of a wild boar killed by a poacher. To convict a suspected poacher, one needs to know the time when the boar was killed. To determine this time, the temperature of the body was measured twice: at noon it was  $60^\circ \text{F}$  and at 1 p. m. it was  $55^\circ \text{F}$ . The air temperature on that day was  $50^\circ \text{F}$  and it did not change since 8 a.m. The normal body temperature of the boar when it is alive is  $90^\circ \text{F}$ . When was the boar killed?

A. 6 a.m.

B. 10 a.m.

C. 10:30 a.m.

D. 11 a.m.

E. 11:30 a.m.

In this case  $M = 50$

Set  $t = 12 \text{ p.m.}$  as  $t = 0$ . We start counting time at  $t = 0$ , which is 12:00 noon.

$$T(0) = 60, \quad T(1) = 55.$$

$$50 - T(t) = (50 - 60) e^{-kt} \quad ; \quad 50 - T(t) = -10 e^{-kt}$$

$$T(t) = 50 + 10 e^{-kt} \quad T(1) = 55$$

$$\text{So } 55 = 50 + 10 e^{-k}$$

$$10 e^{-k} = 5$$

$$e^{-k} = \frac{1}{2}$$

$$\text{So } T(t) = 50 + 10 \left(\frac{1}{2}\right)^t$$

The temperature of the body was 90 at the time the boar was killed

$$90 = 50 + 10 \left(\frac{1}{2}\right)^t \quad 40 = 10 \left(\frac{1}{2}\right)^t \quad \left(\frac{1}{2}\right)^t = 4$$

$$t = -2$$

The boar was killed two hours before

11. Consider the vectors  $v_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} 3 \\ 1 \\ 7 \\ 3 \end{bmatrix}$ ,  $v_3 = \begin{bmatrix} 5 \\ -3 \\ 9 \\ 1 \end{bmatrix}$ ,  $v_4 = \begin{bmatrix} -2 \\ 4 \\ 2 \\ 8 \end{bmatrix}$ . The dimension of

the space  $\text{span}\{v_1, v_2, v_3, v_4\}$  is then equal to

A. 1

B. 2

C. 3

D. 4

E. 5

The dimension of the span of the four vectors is equal to the rank of the

matrix

$$\begin{bmatrix} 1 & 3 & 5 & -2 \\ -1 & 1 & -3 & 4 \\ 1 & 7 & 9 & 2 \\ -1 & 3 & 1 & 8 \end{bmatrix}$$

$R_1 + R_2$

$\rightarrow$

$-R_1 + R_3$

$R_1 + R_4$

$$\begin{bmatrix} 1 & 3 & 5 & -2 \\ 0 & 4 & 2 & 2 \\ 0 & 4 & 4 & 4 \\ 0 & 6 & 6 & 6 \end{bmatrix}$$

$R_2/2$   $R_3/4$

$\rightarrow$

$-R_2/4 + R_4/6$

$$\begin{bmatrix} 1 & 3 & 5 & -2 \\ 0 & 2 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Swap  $R_2 \rightarrow R_3$

$\rightarrow$

$$\begin{bmatrix} 1 & 3 & 5 & -2 \\ 0 & 1 & 1 & 1 \\ 0 & 2 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$-2R_2 + R_3$

$\rightarrow$

$$\begin{bmatrix} 1 & 3 & 5 & -2 \\ 0 & 1 & 1 & 1 \\ 0 & 0 & -1 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Rank = 3

$$M = 6x^2y^2 + 4e^x - 2y \sin 2x; \quad \frac{\partial M}{\partial y} = 12yx^2 - 2 \sin 2x$$

$$N = 4x^3y + \cos 2x, \quad \frac{\partial N}{\partial x} = 12x^2y - 2 \sin 2x$$

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8. Find an implicit solution of the initial value problem:

$$\begin{cases} (6x^2y^2 + 4e^x - 2y \sin 2x) + (4x^3y + \cos 2x) \frac{dy}{dx} = 0, \\ y(0) = 1 \end{cases}$$

$$\frac{\partial F}{\partial x} = 6x^2y^2 + 4e^x - 2y \sin 2x$$

$$F(x, y) = 2x^3y^2 + 4e^x + y \cos 2x + f(y)$$

$$\frac{\partial F}{\partial y} = 4x^3y + \cos 2x + f'(y) = 4x^3y + \cos 2x$$

$$\text{so } f'(y) = 0$$

A.  $2x^3y^2 - y \cos 2x + 4e^x = 3$

B.  $x^3y^2 + y \cos 2x + 4ye^x = 0$

C.  $2x^3y^2 + y \cos 2x + 4e^x = 5$

D.  $x^3y^2 + y^2 \cos 2x + 4e^x = 5$

E.  $2x^3y^2 + y \cos 2x - 4ye^x = -3$

$$F(x, y) = 2x^3y^2 + 4e^x + y \cos 2x = C$$

when  $x=0, y=1$

$$F(0, 1) = 4 + 1 = 5$$

$$\boxed{2x^3y^2 + 4e^x + y \cos 2x = 5}$$

3. The general solution of  $xy' - y = x^2e^x$  is

A.  $y = xe^x + cx$

B.  $y = x^2e^x - xe^x + cx$

C.  $y = xe^x - cx^2$

D.  $y = x^2e^x + xe^x + cx$

E. None of the above

$$y' - \frac{y}{x} = xe^x$$

$$x \frac{d}{dx} (x^{-1}y) = xe^x$$

$$\frac{d}{dx} (x^{-1}y) = e^x$$

$$x^{-1}y = e^x + C$$

$$y(x) = xe^x + Cx$$

6. The solution of

is given by

A.  $x^2y^2 + 4xy = C$

B.  $x^2y^2 + 4x = C$

C.  $xy^2 - 2x = C$

D.  $x^2y^2 - 4x = C$

E.  $xy^2 - 4x = C$

$$y' + \frac{y}{x} = \frac{2}{x^2y}, \quad x \neq 0$$

$$y y' + \frac{1}{x} y^2 = \frac{2}{x^2}$$

$$\frac{1}{2} v' + \frac{1}{2} v = \frac{2}{x^2}$$

$$v' + \frac{2}{x} v = \frac{4}{x^2}$$

$$x^{-2} \frac{d}{dx} (x^2 v) = 4x^{-2}$$

$$x^2 v = 4x + C$$

$$x^2 y^2 - 4x = C$$

multiply the equation  
by  $y$ :

$$v = y^2$$

$$\frac{dv}{dx} = 2y y'$$

$$\frac{d}{dx} (x^2 v) = 4$$

but  $v = y^2$ .

3. Find the explicit solution of the initial value problem

$$y' = \frac{xy^2}{x^2 + 1}, \quad y(0) = 3.$$

$$\frac{dy}{y^2} = \frac{x}{x^2 + 1} dx$$

A.  $\frac{1}{2}(6 + \ln(1 + x^2))$

B.  $\frac{6}{2 - 3\ln(1 + x^2)}$

C.  $\frac{6}{2 + 3\ln(1 + x^2)}$

D.  $\frac{1}{2}(6 - 3\ln(1 + x^2))$

E.  $\frac{1}{3}(9 - 2\ln(1 + x^2))$

$$\int \frac{dy}{y^2} = \int \frac{x}{x^2 + 1} dx$$

$$-\frac{1}{y} = \frac{1}{2} \ln(x^2 + 1) + C.$$

when  $x=0$ ;  $-\frac{1}{3} = C.$

$$-\frac{1}{y} = -\frac{1}{3} + \frac{1}{2} \ln(x^2 + 1)$$

$$\frac{1}{y} = \frac{1}{3} - \frac{1}{2} \ln(1 + x^2)$$

$$\frac{1}{y} = \frac{2 - 3 \ln(1 + x^2)}{6}$$

$$y = \frac{6}{2 - 3 \ln(1 + x^2)}$$

The homogeneous equation is  $y'' + 4y = 0$  and its general solution is  $y_h(x) = c_1 \cos 2x + c_2 \sin 2x$ .

One needs to find a particular solution. Since  $\sin(2t)$  is a solution of the homogeneous eq., one needs to ~~find~~ look

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for  $y_p(x) = A e^{2t} + B t \sin 2t + C t \cos 2t$ .

8. Which of the following is the general solution to  $y'' + 4y = e^{2t} + 12 \sin(2t)$ ?

we look for  $A$ :

Correct

$\rightarrow$  A.  $y(t) = c_1 \cos(2t) + c_2 \sin(2t) + \frac{1}{8} e^{2t} - 3t \cos(2t)$

Not  
this  
one

B.  $y(t) = c_1 e^{2t} + c_2 e^{-2t} + \frac{1}{4} t e^{2t} - 3t \cos(2t)$

C.  $y(t) = c_1 + c_2 e^{-4t} + \frac{1}{12} t e^{2t} - 3t \cos(2t)$

D.  $y(t) = c_1 \cos(2t) + c_2 \sin(2t) + \frac{1}{8} e^{2t} + 3 \sin(2t)$

E. None of the above.

$y_{p2} = B t \sin 2t + C t \cos 2t$ ,  $y'_{p2} = B \sin 2t + C \cos 2t + 2B t \cos 2t - 2C t \sin 2t$

$y''_{p2} = 4B \cos 2t - 4C \sin 2t - 4B t \sin 2t - 4C t \cos 2t$

$y''_{p2} + 4y = 4B \cos 2t - 4C \sin 2t = 12 \sin 2t$   
 $-4C = 12$   
 $C = -3$

So  $y_p(t) = \frac{1}{8} e^{2t} - 3t \cos(2t)$

$y_{p1} = A e^{2t}$   
 $y'_{p1} = 2A e^{2t}$ ;  $y''_{p1} = 4A e^{2t}$   
 $y''_{p1} + 4y_{p1} = 8A e^{2t} = e^{2t}$   $A = \frac{1}{8}$

10. A particular solution of the equation

$$y^{(4)} - y'' = 2 \sin t - 3e^{-t} + 4t$$

is of the form

A.  $y_p(t) = A \cos t + B \sin t + Cte^{-t} + t^2(Dt + E)$

B.  $y_p(t) = t(A \cos t + B \sin t) + Cte^{-t} + t^2(Dt + E)$

C.  $y_p(t) = A \cos t + B \sin t + Ce^{-t} + t^2(Dt + E)$

D.  $y_p(t) = t(A \cos t + B \sin t) + Ce^{-t} + t^2(Dt + E)$

E.  $y_p(t) = t(A \cos t + B \sin t) + Cte^{-t} + t(Dt + E)$

$y_p$  corresponding to  $4t$

$y_p$  corresponding to  $-3e^{-t}$

$$y_p = Ete^{-t}$$

$$y_p = A \sin 2t + B \cos 2t + t^2(Ct + D) + Ete^{-t}$$

$$y = e^{rt}$$

$$r^4 - r^2 = 0$$

$$r^2(r^2 - 1) = 0$$

$$r = 0 \text{ multiplicity } 2$$

$$r = 1, r = -1$$

$y_p$  corresponding to  $\sin 2t$

$$y_p = A \sin 2t + B \cos 2t$$

$$y_p = t^2(Ct + D)$$

9. According to the method of undetermined coefficients, what is the proper form of a particular solution  $Y$  to the following differential equation?

$$y^{(4)} - 4y'' = 24t^2 - 4 - 3te^t.$$

- A.  $Y(t) = At^2 + Bte^t$ .
- B.  $Y(t) = At^2 + Bt + C + Dte^t + Ee^t$ .
- C.  $Y(t) = At^3 + Bt^2 + Ct + D + Ete^t + Fe^t$ .
- D.  $Y(t) = At^4 + Bt^3 + Ct^2 + Dte^t + Ee^t$ .
- E. None of the above.

$y_p$  corresponding to  $24t^2 - 4$   
 $y_p$  corresponding to  $-3te^t$

$$y = e^{rt}$$

$$r^4 - r^2 = r^2(r^2 - 1)$$

$r=0$  multiply 2

$$r=1, r=-1$$

$$y_{PI} = t^2 (A + Bt + Ct^2)$$

$$y_p = t (tD + E) e^t$$

5. How many asymptotically unstable equilibrium solution(s) does the following differential equation have?

$$y' = (y^2 + 1)(y^2 - 1)(y + 2).$$

The real roots are

$$y = -2, y = -1, y = 1$$

A. 0,

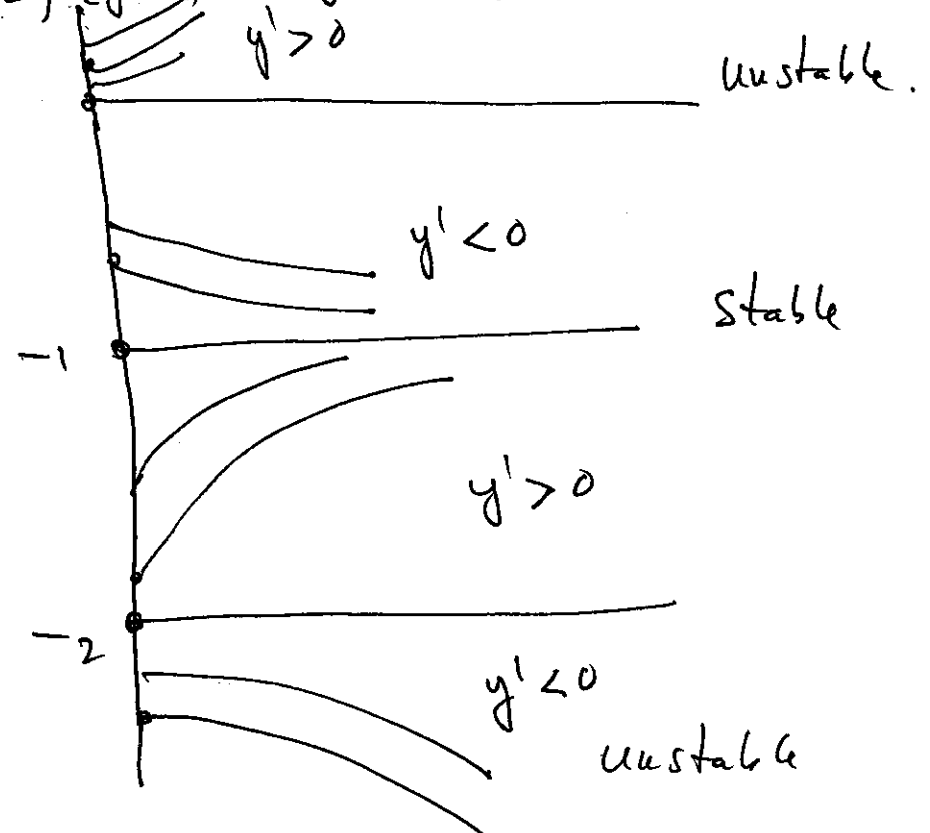
B. 1,

C. 2,

D. 3,

E. None of the above.

$$y' = (y^2 + 1)(y + 2)(y + 1)(y - 1)$$



If  $y < -2$   $y' < 0$

If  $-2 < y < -1$   $y' > 0$

If  $-1 < y < 1$

3. Find the solution  $y(x)$  to

$$\text{Set } y/x = V$$

$$y = x V$$

$$\frac{dy}{dx} = V + x \frac{dV}{dx}$$

$$V + x \frac{dV}{dx} = V + e^{-V}$$

$$x \frac{dV}{dx} = e^{-V}$$

$$e^V dV = \frac{dx}{x}$$

$$e^V = \ln x + c$$

$$\frac{dy}{dx} = e^{-\frac{y}{x}} + \frac{y}{x},$$

$$y(e) = 0.$$

A.  $y(x) = \ln(\ln(x))$

B.  $y(x) = x \ln(\ln(x))$

C.  $y(x) = \ln(\ln(x) + 1) - \ln(2)$

D.  $y(x) = x \ln(x) - e$

E.  $y(x) = x \ln(x) - x$

When  $x = e$ ;  $y(e) = 0$  So  $V(e) = 0$

So  $c = 0$ .

$$e^V = \ln x \quad V = \ln(\ln x)$$

$$y = x \ln(\ln x)$$

14. Using the method of Undetermined Coefficients, which of the following is the correct form of a particular solution  $y_p$  to the nonhomogeneous differential equation

$$y^{(4)} - y = xe^x + 3 \cos x - 4x ?$$

A.  $y_p = x(A + Bx)e^x + (C \cos x + D \sin x) + Ex$

B.  $y_p = (A + Bx)e^x + (C \cos x + D \sin x) + E + Fx$

C.  $y_p = (A + Bx)e^x + x(C \cos x + D \sin x) + x(E + Fx)$

D.  $y_p = x(A + Bx)e^x + x(C \cos x) - Dx$

 E.  $y_p = x(A + Bx)e^x + x(C \cos x + D \sin x) + E + Fx$

9. Find the general solutions to  $y'' + 6y' + 10y = 0$

$$y = e^{rx}$$

$$r^2 + 6r + 10 = 0$$

$$r = \frac{-6 \pm \sqrt{36 - 40}}{2}$$

$$r = \frac{-6 \pm \sqrt{-4}}{2}$$

$$r = -3 \pm i$$

$$y(t) = c_1 e^{-3t} \cos t + c_2 e^{-3t} \sin t$$

A.  $c_1 e^{-2t} \cos(t) + c_2 e^{-2t} \sin(t)$

B.  $c_1 e^{-3t} \cos(t) + c_2 e^{-3t} \sin(t)$

C.  $c_1 e^{-3t} \cos(2t) + c_2 e^{-3t} \sin(2t)$

D.  $c_1 e^{2t} \cos(t) + c_2 e^{2t} \sin(t)$

E.  $c_1 e^{3t} \cos(t) + c_2 e^{3t} \sin(t)$

Eigenvalues:  $\det(A - \lambda I) = \det \begin{bmatrix} -3-\lambda & -4 \\ 1 & 1-\lambda \end{bmatrix} = -(3+\lambda)(1-\lambda) + 4$   
 $= -3 + 3\lambda - \lambda + \lambda^2 + 4$   
 $= \lambda^2 + 2\lambda + 1 = (\lambda + 1)^2.$

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Solution:  $X_1(t) = e^{-t} v_1$

$X_2(t) = e^{-t} (t v_1 + v_2)$

$v_2$  is any vector.  
 such that  $(A + I)v_2 = v_1 \neq 0$

$A + I = \begin{bmatrix} -2 & -4 \\ 1 & 2 \end{bmatrix}$

We pick  $v_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$v_1 = \begin{bmatrix} -2 & -4 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$

7. Find the general solution of the system

$x' = \begin{pmatrix} -3 & -4 \\ 1 & 1 \end{pmatrix} x.$

A.  $c_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^t + c_2 \left[ \begin{pmatrix} 2 \\ 1 \end{pmatrix} t e^t + \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^t \right],$

B.  $c_1 \begin{pmatrix} -2 \\ 1 \end{pmatrix} e^{-t} + c_2 \left[ \begin{pmatrix} -2 \\ 1 \end{pmatrix} t e^{-t} + \begin{pmatrix} -1 \\ 0 \end{pmatrix} e^{-t} \right],$

C.  $c_1 \begin{pmatrix} 2 \\ 1 \end{pmatrix} e^{-t} + c_2 \left[ \begin{pmatrix} 2 \\ 1 \end{pmatrix} t e^{-t} + \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^{-t} \right],$

→ D.  $c_1 \begin{pmatrix} -2 \\ 1 \end{pmatrix} e^{-t} + c_2 \left[ \begin{pmatrix} -2 \\ 1 \end{pmatrix} t e^{-t} + \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^{-t} \right],$

E.  $c_1 \begin{pmatrix} -2 \\ 1 \end{pmatrix} e^t + c_2 \left[ \begin{pmatrix} -2 \\ 1 \end{pmatrix} t e^t + \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^t \right].$

So  $X_1(t) = e^{-t} \begin{bmatrix} -2 \\ 1 \end{bmatrix}$

$X_2(t) = e^{-t} \left( t \begin{bmatrix} -2 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)$

2. Find the number of **stable** critical points for the autonomous equation

$$\frac{dx}{dt} = x(x-1)^2(x+3)(x^2-4) = F(x) = (x+3)(x+2)x(x-1)^2(x-2)$$

A. 1

B. 2

C. 3

D. 4

E. 0

the critical points are the  
zeros of  $F(x)$ :  $-3, -2, 0, 1, 2$

When  $x < -3$ ,  $F(x) > 0$

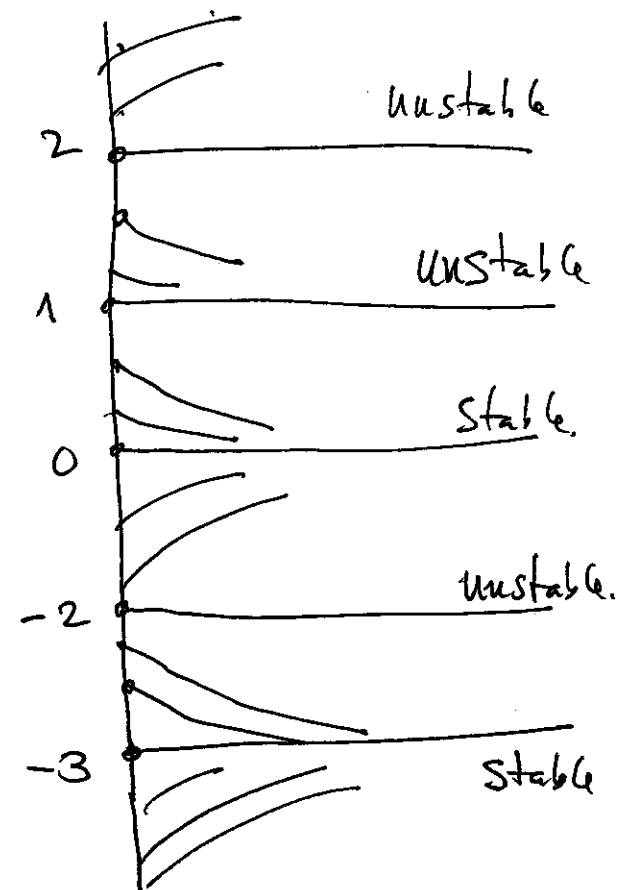
$-3 < x < -2$ ,  $F(x) < 0$

$-2 < x < 0$ ,  $F(x) > 0$

$0 < x < 1$ ,  $F(x) < 0$

$1 < x < 2$ ,  $F(x) < 0$

$x > 2$ ,  $F(x) > 0$



16. One eigenvalue of  $\begin{bmatrix} 1 & 2 & 2 \\ -1 & 4 & 1 \\ 0 & 0 & 3 \end{bmatrix}$  is  $\lambda = 3$ . A basis for the corresponding eigenspace is

$$(A - 3I)V = 0 \quad \begin{bmatrix} -2 & 2 & 2 \\ -1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

A.  $\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} \right\}$

B.  $\left\{ \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

→ C.  $\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \right\}$

D.  $\left\{ \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} \right\}$

E.  $\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$

$$-v_1 + v_2 + v_3 = 0 \quad v_1 = v_2 + v_3$$

$$V = \begin{bmatrix} v_2 + v_3 \\ v_2 \\ v_3 \end{bmatrix} = v_2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + v_3 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

One basis is  $\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}; \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

but if we add the two vectors

$$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}; \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix} \text{ is another basis}$$

17. If  $y(x)$  is a solution of  $y'' - 2y' + y = 0$  satisfying  $y(0) = 1$  and  $y'(0) = -1$ , then  $y(\frac{1}{2}) =$

A. 0

B.  $-e^{\frac{1}{2}}$

C.  $e^{\frac{1}{2}}$

D.  $2e^{\frac{1}{2}}$

E.  $-3e^{\frac{1}{2}}$

$$y = e^{rx} ; \quad r^2 - 2r + 1 = 0 \quad (r-1)^2 = 0$$

$$y(x) = Ae^x + Bxe^x$$

$$y(0) = A = 1$$

$$y'(x) = Ae^x + Be^x + Bxe^x$$

$$y'(0) = A + B = -1 \quad B = -2$$

$$y(x) = e^x - 2xe^x$$

$$y(\frac{1}{2}) = e^{\frac{1}{2}} (1 - 2 \cdot \frac{1}{2}) = 0$$

Step 1: Find eigenvalues.  $\det \begin{bmatrix} 3-\lambda & 5 \\ -1 & -1-\lambda \end{bmatrix} = (3-\lambda)(-1-\lambda) + 5 = \lambda^2 - 2\lambda + 2 = 0$   
 $\lambda = \frac{2 \pm \sqrt{-4}}{2} = 1 \pm i$

Step 2: Find eigenvectors.

$\lambda = 1+i$ ,  $(A - \lambda I)v = \begin{bmatrix} (2-i) & 5 \\ -1 & -(2+i) \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$  Page 19

$v_1 + (2+i)v_2 = 0 \quad v_1 = -(2+i)v_2$

24. The general solution of  $x' = \begin{bmatrix} 3 & 5 \\ -1 & -1 \end{bmatrix} x$  has the form

$v = \begin{bmatrix} -2-i \\ 1 \end{bmatrix}$

$x(t) = e^{(1+i)t} \begin{bmatrix} -2-i \\ 1 \end{bmatrix}$

→ A.  $c_1 e^t \begin{bmatrix} 2 \cos t - \sin t \\ -\cos t \end{bmatrix} + c_2 e^t \begin{bmatrix} \cos t + 2 \sin t \\ -\sin t \end{bmatrix}$

B.  $c_1 e^t \begin{bmatrix} \cos t \\ 2 \cos t - \sin t \end{bmatrix} + c_2 e^t \begin{bmatrix} -\sin t \\ \cos t - 2 \sin t \end{bmatrix}$

C.  $c_1 e^t \begin{bmatrix} 2 \cos t + \sin t \\ -\cos t \end{bmatrix} + c_2 e^t \begin{bmatrix} \cos t + 2 \sin t \\ \sin t \end{bmatrix}$

D.  $c_1 e^t \begin{bmatrix} \cos t - 2 \sin t \\ \sin t \end{bmatrix} + c_2 e^t \begin{bmatrix} 2 \cos t + \sin t \\ -\cos t \end{bmatrix}$

E. None of the above.

The real and imaginary parts will give two L.I. real solutions.

$x(t) = e^t (\cos t + i \sin t) \begin{bmatrix} -2-i \\ 1 \end{bmatrix} = e^t \begin{bmatrix} -2 \cos t + \sin t - i (\cos t + 2 \sin t) \\ \cos t + i \sin t \end{bmatrix}$   
 $= e^t \begin{bmatrix} -2 \cos t + \sin t \\ \cos t \end{bmatrix} + i e^t \begin{bmatrix} -\cos t - 2 \sin t \\ \sin t \end{bmatrix}$

The method of variation of parameters gives that

$$u_1' = -\frac{1}{w(y_1, y_2)} y_2 f; \quad u_2' = \frac{1}{w(y_1, y_2)} y_1 f.$$

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$$W(y_1, y_2) = \begin{bmatrix} e^{2x} & e^{-2x} \\ 2e^{2x} & -2e^{-2x} \end{bmatrix} = -4.$$

7. If  $y = u_1 y_1 + u_2 y_2$  where  $y_1 = e^{2x}$  and  $y_2 = e^{-2x}$  is a particular solution of

$$y'' - 4y = 4 \tan x$$

then  $u_1$  and  $u_2$  are determined by

—→ A.  $u_1' = e^{-2x} \tan x$   $u_2' = -e^{2x} \tan x$

B.  $u_1' = -e^{-2x} \sec^2 x$   $u_2' = e^{2x} \sec^2 x$

C.  $u_1' = -2 \sin 2x \tan x$   $u_2' = 2 \cos 2x \tan x$

D.  $u_1' = 2 \sin 2x \tan x$   $u_2' = -2 \cos 2x \tan x$

E.  $u_1' = \tan x$   $u_2' = 0$

So  $u_1'(x) = \frac{1}{4} e^{-2x} (4 \tan x)$

$$u_1'(x) = e^{-2x} \tan x$$

$$u_2'(x) = -\frac{1}{4} e^{2x} \cdot (4 \tan x)$$

$$u_2'(x) = -e^{2x} \tan x.$$

10. Find all values of  $a$  such that the following system of equations has exactly one solution.

$$\begin{cases} x + y - z = 2 \\ x + 2y + z = 3 \\ x + y + (a^2 - 5)z = a \end{cases}$$

$$\left[ \begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 1 & 2 & 1 & 3 \\ 1 & 1 & a^2-5 & a \end{array} \right] \begin{array}{l} -R_1 + R_2 \\ \longrightarrow \\ -R_1 + R_3 \end{array}$$

$$\left[ \begin{array}{ccc|c} 1 & 1 & -1 & 2 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & a^2-4 & a-2 \end{array} \right]$$

If  $a^2 - 4 \neq 0$  the system has only one solution.

A.  $a \neq 2$  and  $a \neq -2$

B.  $a = 2$  or  $a = -2$

C.  $a = -2$

D.  $a = \pm\sqrt{5}$

E.  $a \neq 0$

If  $a^2 = 4$  we have two possibilities  
 $a = 2$ : In this case we have infinitely many solutions  
 $a = -2$  We have no solution.

17. Determine all values of  $k$  such that the vectors  $(1, -1, 0)$ ,  $(1, 2, 2)$ ,  $(0, 3, k)$  are a basis for  $\mathbb{R}^3$ .

$$\det \begin{bmatrix} 1 & 1 & 0 \\ -1 & 2 & 3 \\ 0 & 2 & k \end{bmatrix} = \det \begin{bmatrix} 1 & 1 & 0 \\ 0 & 3 & 3 \\ 0 & 2 & k \end{bmatrix}$$

$$= 3k - 6 \neq 0 \quad k \neq 2$$

A.  $k = 1$

B.  $k = 2$

C.  $k \neq 2$

D.  $k \neq 1$

E.  $k \neq 3$

11. Let  $y(x)$  be the solution of the initial value problem

$$y'' + y = x, \\ y(0) = 1, \quad y'(0) = 2.$$

Then  $y(\pi)$  is equal to

A.  $y(\pi) = \pi$

B.  $y(\pi) = 2\pi$

C.  $y(\pi) = \pi - 1$

D.  $y(\pi) = 2\pi + 1$

E.  $y(\pi) = \pi + 1$

take  $y_p = Ax + B$

$$y_p'' = 0 \quad A = 1, \quad B = 0$$

$$y(x) = A \cos x + B \sin x + x.$$

$$y(0) = A = 1$$

$$y'(0) = B + 1 = 2 \quad B = 1$$

$$y(x) = \cos x + \sin x + x.$$

$$y(\pi) = \pi - 1$$

(\*)  $y(x) = 1 + e^x - \sin x + \cos x$   
 $y(\pi) = e^\pi$

12. Let  $y(x)$  satisfy

① Solve the homogeneous eq.

$$y = e^{rx}$$

$$r^2 - r = 0$$

$$r = 0, r = 1$$

$$y'' - y' = 2 \sin(x),$$

$$y(0) = 3, y'(0) = 0.$$

$$y_h = A_1 + B_2 e^x$$

Then  $y(\pi)$  is equal to:

A.  $e^\pi + 10$

B.  $e^\pi + 1$

C.  $e^\pi + 2$

D.  $e^\pi + 3$

E.  $e^\pi$

② Find a particular solution.

$$y_p(x) = A \sin x + B \cos x$$

$$y_p' = A \cos x - B \sin x$$

$$y_p'' = -A \sin x - B \cos x$$

$$y_p'' - y_p' = -A \sin x - B \cos x - A \cos x + B \sin x = \cos x (-A - B) + \sin x (B - A)$$

We want  $A + B = 0$  ;  $B - A = 2$   $B = 1, A = -1$

$$y(x) = C_1 + C_2 e^x - \sin x + \cos x$$

$$y'(x) = C_2 e^x - \cos x - \sin x$$

$$y(0) = C_1 + C_2 + 1 = 3$$

$$y'(0) = C_2 - 1 = 0$$

$C_2 = 1, C_1 = 1$   
 Go to the top (\*)

12. For the system  $\mathbf{x}' = \begin{bmatrix} 5 & 5 \\ -8 & -7 \end{bmatrix} \mathbf{x}$ , the origin is

- A. a saddle point
- B. a proper node source
- C. a center point
- D. a spiral sink
- E. a spiral source

$$\det(A - \lambda I) = \det \begin{bmatrix} 5 - \lambda & 5 \\ -8 & -7 - \lambda \end{bmatrix}$$

$$= (5 - \lambda)(-7 - \lambda) + 40$$

$$= (7 + \lambda)(\lambda - 5) + 40$$

$$= \lambda^2 + 2\lambda + 5 = 0$$

$$\lambda = \frac{-2 \pm \sqrt{4 - 20}}{2}$$

$$\lambda = \frac{-2 \pm 4i}{2}$$

$$\lambda = -1 \pm 2i$$

Complex eigenvalues  
with negative  
Real part.

15. The solution curves of the system

$$X'(t) = \begin{bmatrix} 1 & 1 \\ 1 & -2 \end{bmatrix} X(t),$$

where  $X(t) = \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$ , have the following structure near the origin  $x_1 = x_2 = 0$ :

A. A saddle point

B. A nodal sink

C. A nodal source

D. A center

E. parallel lines.

$$\det \begin{bmatrix} 1 - \lambda & 1 \\ 1 & -2 - \lambda \end{bmatrix}$$

$$= (\lambda + 2)(\lambda - 1) - 1$$

$$= \lambda^2 + \lambda - 3 = 0$$

$$\lambda = \frac{-1 \pm \sqrt{1 + 12}}{2}$$

$$\lambda = \frac{-1 + \sqrt{13}}{2}, \quad \lambda = \frac{-1 - \sqrt{13}}{2}$$

Real eigenvalues with opposite signs

16. Let  $X(t) = \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$ . Find all the values of  $a$  so that the origin  $x_1 = x_2 = 0$

$$X'(t) = \begin{bmatrix} a & -27 \\ 3 & 0 \end{bmatrix} X(t)$$

is a spiral source of the system, that is, the solution curves are spirals approaching infinity as  $t \rightarrow \infty$ ?

A.  $0 < a < 27$

B.  $0 < a < 18$

C.  $-18 < a < 18$

D.  $0 > a > -18$

E.  $0 > a > -27$

The origin is a spiral if the eigenvalues are complex and have positive ~~part~~ real part.

$$A = \begin{bmatrix} a & -27 \\ 3 & 0 \end{bmatrix}$$

$$\det(A - \lambda I) = \det \begin{bmatrix} a - \lambda & -27 \\ 3 & -\lambda \end{bmatrix} = -\lambda(a - \lambda) + 81$$

$$= \lambda^2 - a\lambda + 81 \quad \text{the roots are}$$

$$\lambda = \frac{1}{2}(a \pm \sqrt{a^2 - 4 \times 81})$$

So we must have  $a > 0$  because the real part is  $a/2$  and  $a^2 - 4 \times 81 < 0$  So the eigenvalues are imaginary  $0 < a < \sqrt{4 \times 81} = 18$

Step 1:  $\det(A - \lambda I) = \begin{vmatrix} 1-\lambda & 6 \\ 1 & 2-\lambda \end{vmatrix} = (1-\lambda)(2-\lambda) - 6 = \lambda^2 - 3\lambda - 4 = (\lambda - 4)(\lambda + 1)$

$\lambda = -1$ :  $\begin{bmatrix} 2 & 6 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} \quad v_2 = -3v_1 \quad v = \begin{bmatrix} -3 \\ 1 \end{bmatrix}$

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$\lambda = 4$ :  $\begin{bmatrix} -3 & 6 \\ 1 & -2 \end{bmatrix} \quad v_1 = 2v_2 \quad v = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

$$X(t) = c_1 e^{-t} \begin{bmatrix} -3 \\ 1 \end{bmatrix} + c_2 e^{4t} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$X(0) = \begin{bmatrix} -1 \\ 2 \end{bmatrix} \quad \begin{aligned} -3c_1 + 2c_2 &= -1 \\ c_1 + c_2 &= 2 \end{aligned}$$

17. Let  $X(t) = \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$  satisfy

$$X'(t) = \begin{bmatrix} 1 & 6 \\ 1 & 2 \end{bmatrix} X(t), \quad X(0) = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

The limit  $S = \lim_{t \rightarrow \infty} \frac{x_2'(t)}{x_1'(t)}$ , which is the slope of the curve  $X(t)$  as  $t \rightarrow \infty$ , is equal to

A.  $S = -3$

B.  $S = \frac{1}{2}$

C.  $S = -\frac{1}{3}$

D.  $S = -\frac{1}{2}$

E.  $S = 3$

$c_1 = c_2 = 1$

$$X(t) = e^{-t} \begin{bmatrix} -3 \\ 1 \end{bmatrix} + e^{4t} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

the slope  $= \frac{1}{2}$

as  $t \rightarrow \infty \quad X(t) \rightarrow e^{4t} \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

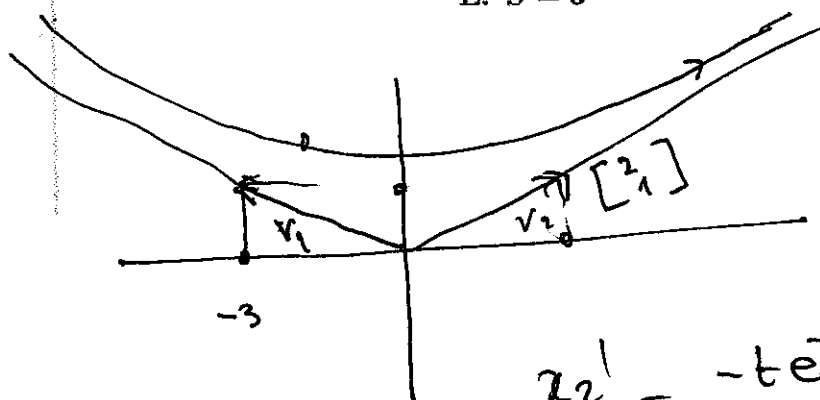
one can also check:

$$x_2(t) = e^{-t} + e^{4t}$$

$$x_1 = -3e^{-t} + 2e^{4t}$$

$$\lim_{t \rightarrow \infty} \frac{x_2'}{x_1'} = \frac{4}{8} = \frac{1}{2}$$

$$\frac{x_2'}{x_1'} = \frac{-te^{-t} + 4e^{4t}}{3e^{-t} + 8e^{4t}}$$



15. Which of the following matrices are nondefective:

$$A = \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}, \quad C = \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}?$$

A. A, B

B. A, C

C. B only

D. C only

E. A only

For  $2 \times 2$  matrices, being nondefective is the same as having two distinct eigen values.

$$\det(A - \lambda I) = \det \begin{bmatrix} 1-\lambda & 2 \\ 0 & 3-\lambda \end{bmatrix} = (1-\lambda)(3-\lambda)$$

Eigenvalues  $\lambda = 1$   
 $\lambda = 3$

$$\det(B - \lambda I) = \det \begin{bmatrix} 1-\lambda & 2 \\ 0 & 1-\lambda \end{bmatrix} = (1-\lambda)^2$$

Eigenvalue  $\lambda = 1$ .

$$\det(C - \lambda I) = \det \begin{bmatrix} 1-\lambda & 1 \\ 0 & -\lambda \end{bmatrix} = -\lambda(1-\lambda)$$

$\lambda = 0, \lambda = 1$

A and C are nondefective B is defective.

22. The eigenvalues of the matrix  $A = \begin{bmatrix} 3 & 0 & 0 \\ -2 & 3 & -2 \\ 2 & 0 & 5 \end{bmatrix}$  are 3 and 5. One of the associated eigenspaces has dimension one. This eigenspace has basis:

$$(A - 3I)v = \begin{bmatrix} 0 & 0 & 0 \\ -2 & 0 & -2 \\ 2 & 0 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$2v_1 + 2v_3 = 0 \quad v_1 = -v_3$$

$$V = \begin{bmatrix} v_1 \\ v_2 \\ -v_1 \end{bmatrix} = v_1 \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} + v_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

Eigenspace has dimension two

$$(A - 5I)v = \begin{bmatrix} -2 & 0 & 0 \\ -2 & -2 & -2 \\ 2 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$v_1 = 0, \quad -2v_2 - 2v_3 = 0 \quad v_2 = -v_3$$

$$V = \begin{bmatrix} 0 \\ v_2 \\ -v_2 \end{bmatrix} = v_2 \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$$

A.  $\begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$

B.  $\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

C.  $\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

D.  $\begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$

E.  $\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$

8. Let  $A = \begin{bmatrix} -1 & 0 & 0 \\ 1 & 5 & -1 \\ 1 & 6 & -2 \end{bmatrix}$ . Let  $\lambda_1, \lambda_2$  and  $\lambda_3$  denote the eigenvalues of  $A$  and let  $E_1, E_2$  and  $E_3$  denote the corresponding eigenspaces. Which of the following is correct?

A.  $\lambda_1 = 2, \lambda_2 = 3$  and  $\lambda_3 = -1, \dim E_1 = \dim E_2 = \dim E_3 = 1$

B.  $\lambda_1 = \lambda_2 = -1, \lambda_3 = 4, \dim E_1 = \dim E_2 = 2, \dim E_3 = 1$

C.  $\lambda_1 = \lambda_2 = -1, \lambda_3 = 4, \dim E_1 = \dim E_2 = 1, \dim E_3 = 1$

D.  $\lambda_1 = 1, \lambda_2 = \lambda_3 = 4, \dim E_1 = 1, \dim E_2 = \dim E_3 = 2$

E.  $\lambda_1 = \lambda_2 = -1, \lambda_3 = 3, \dim E_1 = \dim E_2 = 2, \dim E_3 = 1$

$$\underline{\lambda = -1}: (A + I)v = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 6 & -1 \\ 1 & 6 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$v_1 + 6v_2 - v_3 = 0$$

$$\lambda_1 = \lambda_2 = -1$$

$$v_3 = v_1 + 6v_2$$

$$\boxed{\dim E_1 = \dim E_2 = 2}$$

$$v = \begin{bmatrix} v_1 \\ v_2 \\ v_1 + 6v_2 \end{bmatrix} = v_1 \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + v_2 \begin{bmatrix} 0 \\ 1 \\ 6 \end{bmatrix}$$

$\dim E_3$  must be 1

$$\det(A - \lambda I) = \det \begin{bmatrix} -1-\lambda & 0 & 0 \\ 1 & 5-\lambda & -1 \\ 1 & 6 & -2-\lambda \end{bmatrix}$$

$$= -(1+\lambda) \cdot ((5-\lambda)(-2-\lambda) + 6)$$

$$= -(1+\lambda) (-10 - 5\lambda + 2\lambda + \lambda^2 + 6)$$

$$= -(1+\lambda) (\lambda^2 - 3\lambda - 4)$$

$$= -(1+\lambda) (\lambda+1) (\lambda-4)$$

$$= -(1+\lambda)^2 (\lambda-4)$$

15. Let  $A$  be a  $2 \times 2$  matrix whose entries are real numbers. If  $\lambda = 2 + 3i$  is a complex eigenvalue of  $A$  with corresponding complex eigenvector  $\mathbf{w} = \begin{bmatrix} 1-i \\ 4 \end{bmatrix}$ , then the general solution to  $\mathbf{x}' = A\mathbf{x}$  is:

~~A.~~  $\mathbf{x} = C_1 e^{2t} \begin{bmatrix} \cos 3t + \sin 3t \\ 4 \cos 3t \end{bmatrix} + C_2 e^{2t} \begin{bmatrix} \sin 3t - \cos 3t \\ 4 \sin 3t \end{bmatrix}$

B.  $\mathbf{x} = C_1 e^{2t} \begin{bmatrix} \cos 3t - \sin 3t \\ 4 \cos 3t \end{bmatrix} + C_2 e^{2t} \begin{bmatrix} \sin 3t - \cos 3t \\ 4 \sin 3t \end{bmatrix}$

C.  $\mathbf{x} = C_1 e^{3t} \begin{bmatrix} \cos 2t + \sin 2t \\ 4 \cos 2t \end{bmatrix} + C_2 e^{3t} \begin{bmatrix} \sin 2t - \cos 2t \\ 4 \sin 2t \end{bmatrix}$

D.  $\mathbf{x} = C_1 e^{2t} \begin{bmatrix} \cos 3t + \sin 3t \\ 4 \cos 3t \end{bmatrix} + C_2 e^{2t} \begin{bmatrix} \sin 3t + \cos 3t \\ 4 \sin 3t \end{bmatrix}$

E.  $\mathbf{x} = C_1 e^{2t} \begin{bmatrix} \cos 3t + \sin 3t \\ 4 \cos 3t \end{bmatrix} + C_2 e^{2t} \begin{bmatrix} \sin 3t - \cos 3t \\ -4 \sin 3t \end{bmatrix}$

We need to find the real and imaginary parts of the

Complex Solution  
 $\mathbf{x}(t) = e^{(2+3i)t} \begin{bmatrix} 1-i \\ 4 \end{bmatrix}$

$$= e^{2t} (\cos(3t) + i \sin(3t)) \begin{bmatrix} 1-i \\ 4 \end{bmatrix} =$$

$$= e^{2t} \begin{bmatrix} \cos(3t) - i \cos(3t) + i \sin(3t) + \sin(3t) \\ 4 \cos(3t) + 4i \sin(3t) \end{bmatrix} =$$

$$= e^{2t} \underbrace{\begin{bmatrix} \cos(3t) + \sin(3t) \\ 4 \cos(3t) \end{bmatrix}}_{\mathbf{x}_1(t)} + i e^{2t} \underbrace{\begin{bmatrix} \sin(3t) - \cos(3t) \\ 4 \sin(3t) \end{bmatrix}}_{\mathbf{x}_2(t)}$$

Real solution

General Solution:

$$\mathbf{x}(t) = C_1 e^{2t} \begin{bmatrix} \cos(3t) + \sin(3t) \\ 4 \cos(3t) \end{bmatrix} + C_2 e^{2t} \begin{bmatrix} \sin(3t) - \cos(3t) \\ 4 \sin(3t) \end{bmatrix}$$

17. Let  $\mathbf{x}(t) = \begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix}$  be the solution of the system of differential equations

$$\mathbf{x}' = A\mathbf{x}, \quad A = \begin{bmatrix} 4 & -3 \\ 6 & -7 \end{bmatrix}.$$

with the initial data  $\mathbf{x}(0) = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$ . Given that the eigenvalues of  $A$  and their correspond-

ing eigenvectors of  $A$  are  $\lambda_1 = -5$ ,  $V_1 = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$  and  $\lambda_2 = 2$ ,  $V_2 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$ , find  $x_1(1)$ .

A.  $3e^2$

B.  $-2e^{-5}$

C.  $e^{-5}$

D.  $-3e^{-5}$

E.  $e^{-5} + 3e^2$

The general solution is

$$\mathbf{x}(t) = c_1 e^{-5t} \begin{bmatrix} 1 \\ 3 \end{bmatrix} + c_2 e^{2t} \begin{bmatrix} 3 \\ 2 \end{bmatrix}.$$

$$\mathbf{x}(0) = c_1 \begin{bmatrix} 1 \\ 3 \end{bmatrix} + c_2 \begin{bmatrix} 3 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix} \quad \begin{bmatrix} 1 & 3 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

$$\left[ \begin{array}{cc|cc} 1 & 3 & 1 & 1 \\ 3 & 2 & 1 & 3 \end{array} \right] \xrightarrow{-3R_1 + R_2} \left[ \begin{array}{cc|cc} 1 & 3 & 1 & 1 \\ 0 & -7 & 1 & 0 \end{array} \right] \quad \begin{matrix} c_2 = 0 \\ c_1 = 1 \end{matrix}$$

$$\mathbf{x}(t) = e^{-5t} \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

So  $x_1(t) = e^{-5t}$   
 $x_2(t) = 3e^{-5t}$

19. Find all constants  $b$  such that the origin is a spiral source of the system

$$X'(t) = \begin{bmatrix} 3 & b \\ 1 & 4 \end{bmatrix} X(t), \quad b \in \mathbb{R}$$

are

A.  $b < -\frac{1}{3}$

B.  $b > -\frac{1}{3}$

C.  $-\frac{1}{4} < b < -\frac{1}{4}$

D.  $b > -\frac{1}{4}$

E.  $b < -\frac{1}{4}$

Find the eigen values:

$$\det \begin{bmatrix} 3-\lambda & b \\ 1 & 4-\lambda \end{bmatrix} = (3-\lambda)(4-\lambda) - b$$

$$\lambda^2 - 7\lambda + 12 - b = 0$$

$$= 12 - 3\lambda - 4\lambda + \lambda^2 - b = 0;$$

$$\lambda = \frac{7 \pm \sqrt{49 - 4(12-b)}}{2} = \frac{7 \pm \sqrt{1+4b}}{2}$$

We want  $1+4b < 0$

$$4b < -1 \quad b < -\frac{1}{4}$$

The origin is a spiral source if the eigen values are complex and have positive real part

16. Given that  $\lambda = 1$  is a defective eigenvalue of the matrix  $\begin{bmatrix} 2 & -1 \\ 1 & 0 \end{bmatrix}$ , which of the following is the solution of the initial value problem:

$$\mathbf{x}' = \begin{bmatrix} 2 & -1 \\ 1 & 0 \end{bmatrix} \mathbf{x} \quad \mathbf{x}(0) = \begin{bmatrix} 4 \\ 2 \end{bmatrix}?$$

A.  $\mathbf{x}(t) = 2e^t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + e^t \left\{ t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 2 \\ 0 \end{bmatrix} \right\}$

B.  $\mathbf{x}(t) = 2e^t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2te^t \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

C.  $\mathbf{x}(t) = 2e^t \begin{bmatrix} 1 \\ -1 \end{bmatrix} + 2e^t \left\{ t \begin{bmatrix} 1 \\ -1 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$

→ D.  $\mathbf{x}(t) = 2e^t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2e^t \left\{ t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right\}$

E.  $\mathbf{x}(t) = e^t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + e^t \left\{ t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 3 \\ 1 \end{bmatrix} \right\}$

We know that  $\lambda = 1$  is a defective eigenvalue. The linearly independent solutions are

$$\mathbf{x}_1(t) = e^t \mathbf{v}_1 \quad \text{and} \quad \mathbf{x}_2(t) = e^t (t\mathbf{v}_1 + \mathbf{v}_2)$$

where  $\mathbf{v}_2$  is any vector such that  $(A - I)\mathbf{v}_2 = \mathbf{v}_1 \neq 0$

$$A - I = \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix}$$

take  $\mathbf{v}_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

then  $\mathbf{v}_1 = (A - I)\mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

So  $\mathbf{x}_1(t) = e^t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ ;  $\mathbf{x}_2(t) = e^t \left( t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)$

$$\mathbf{x}(t) = c_1 e^t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 e^t \left( t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right) \quad \mathbf{x}(0) = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$$

$$c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + c_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 4 \\ 2 \end{bmatrix}$$

so  $c_1 = c_2 = 2$ .

$$\boxed{\mathbf{x}(t) = 2e^t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2e^t \left( t \begin{bmatrix} 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right)}$$

20. The general solution of the system

$$\mathbf{x}' = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{bmatrix} \mathbf{x}$$

is given by

~~A.~~  $\mathbf{x}(t) = ae^t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + be^t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + ce^{2t} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$

B.  $\mathbf{x}(t) = ae^t \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + be^{-t} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + ce^{2t} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$

C.  $\mathbf{x}(t) = ae^t \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + be^t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + ce^{2t} \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$

D.  $\mathbf{x}(t) = ae^t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + be^t \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} + ce^{2t} \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}$

E.  $\mathbf{x}(t) = ae^{2t} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + be^{2t} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + ce^t \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$

We find the eigenvalues  
 $\det \begin{bmatrix} 1-\lambda & 0 & 1 \\ 0 & 1-\lambda & 2 \\ 0 & 0 & 2-\lambda \end{bmatrix}$

$$= (1-\lambda)^2(2-\lambda)$$

$$\lambda=1, \lambda=2.$$

When  $\lambda=1$  Find the eigenvectors.

$$(A-I)\mathbf{v} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$v_3 = 0$$

$$\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ 0 \end{bmatrix} = v_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + v_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

$$\mathbf{v} = v_1 \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

$$\underline{\lambda=2}: (A-2I)\mathbf{v} = \begin{bmatrix} -1 & 0 & 1 \\ 0 & -1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$

$$-v_1 + v_3 = 0, \quad -v_2 + 2v_3 = 0$$

$$v_1 = v_3$$

$$v_2 = 2v_3$$

General Solution:

$$\mathbf{x}(t) = c_1 e^t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + c_2 e^t \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + c_3 e^{2t} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$